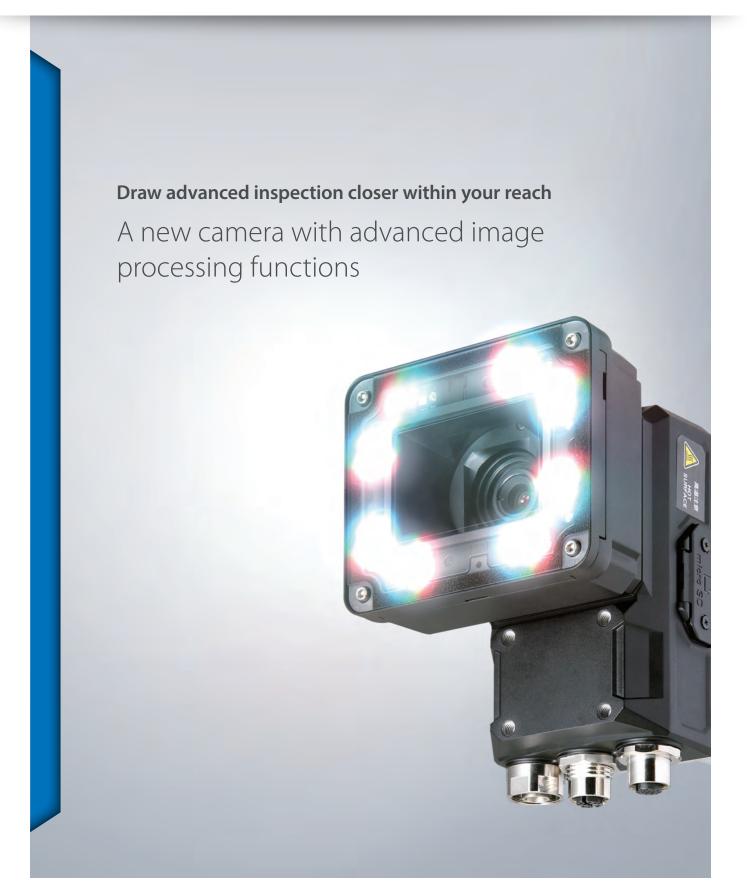


# Smart Camera FHV7 Series



GUM

5% 30. 100 - 20

# The functionality and speed that your production site demands packed in an all-in-one device

The FHV7 Smart Camera is an all-in-one camera with the functionalities of the high-spec vision system FH Series packed in its compact, robust body that is easy to deploy. It provides almost all inspection and measurement functions of the FH Series, and allows for easier image inspections of matching quality, even in processes where inspection had previously been omitted due to restrictions in durability, space, and system deployment time.

Integrated controller structure

Smart camera FHV7 Series

Difficulties in processing product variation

Flexibly accommodates object changes

P.6

Harsh installation environments

A robust all-in-one body that makes it easy to install

P.4

0

Urgent need to improve manufacturing quality

1

0

Excellent productivity performance

P.8

# A robust all-in-one body that makes it easy to install

# Installable anywhere

#### Integrated camera/controller structure

Integrates everything you need for image processing. All-in-one structure includes not only the controller but the lens and lights as well, allowing you to easily attach it wherever you want additional inspections or measurements, without having to worry about control panel space.





# 



## **Robust structure**

#### IP67 waterproof structure

IP67 compatible to allow use in wet conditions, such as regular wash-downs at the sites where the cameras are installed.

#### **Captive screws**

Replaceable modules use captive screws, to prevent problems caused by the screws falling into the production line, etc.

#### **Replaceable covers**

The light cover and optical filter are easy to remove and replace, so you don't need a protective cover, etc., against dirt.





Dirty cover filters can be removed separately for replacement

# **High scalability**

#### **External lights supported**

The FLV and FL Series have a broad lineup of more than 150 models, and they can easily be attached as external lights to FHV7 Smart Cameras. By connecting the lighting controller, you can, from FHV7's setting window, easily adjust the light emission intensity and set light emissions to synchronize with the release of the shutter.



# Flexibly accommodates object changes



# Multi-color Light Accommodates color variations

Multi-color light provides a quick solution to the issue of measuring different colors. For example, objects with variously colored packages on a production line are properly measured with the light that changes its illumination color to fit each object. When the product design is changed or a new models is added, you can simply change a parameter instead of replacing or fine-tuning lights. The production line is always ready for a wider variety of product.

## Autofocus Lens Accommodates size variations

The autofocus lens covers a focal length range from 59 mm to 2,000 mm<sup>\*1</sup>. Even when products in different sizes are produced, the focus range can be changed easily by parameters. <sup>\*2</sup> This feature eliminates mechanical operation for changeover during product replacement, leading to a simpler system with higher productivity.

\*1. Differs depending on the lens type. See the optical chart on page 32 for details.
\*2. Set focuses for different product heights in advance and switch between them when you perform a changeover.



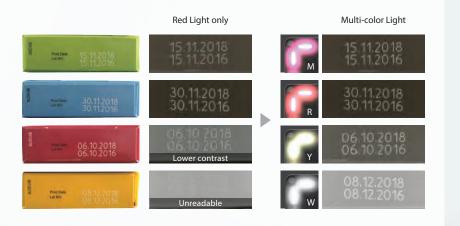
# Best-in-class resolution<sup>\*3</sup>: 12 megapixels Location variation

The image sensor with a 12 megapixels enables highprecision inspections for wider areas. This eliminates the need for installing multiple cameras or a mechanism to move a camera to capture different inspection points on different models on the same production line.

\*3. Based on Omron investigation in October 2018.

# When inspecting products of different colors

As a product has more color options, some of the colors may cause low contrast under a single color illumination. The multi-color illumination allows switching colors for different product color options, ensuring stable inspections.



Working distance 90mm→100mm

# When inspecting products of different sizes

When inspecting products such as plastic bottles that come in different sizes, you can perform a changeover only by switching the setting of the autofocus lens. The autofocus lens does not need the mechanism for moving the camera.



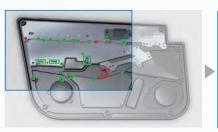


Always in focus even when the focal length changes



# Expanding the range of parts inspection

Accurate and extensive inspection of parts mounting points on different automobile models is enabled without moving cameras. 5 Mpix







# Excellent productivity performance

#### Best-in-class speed\*1

Image capture Maximum speed 2.3 ms

Distributed processing across 2 cores

 $\times$ 

High-speed algorithm

# High-speed processing

The all-in-one FHV7 Smart Camera is packed with capabilities garnered through the FH Series. Its high performance, comparable to a dedicated image processing system, supports advanced applications as well.

# 

# Clear images facilitate inspection

The FHV7 Smart Camera can measure 1.6 megapixels in 24 ms.

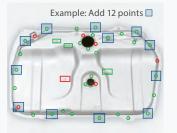
0.4 Mpix

It can perform high-resolution inspections without compromising speed capabilities, and can be used in places where image processing systems are currently deployed.



# More inspection points

FHV7's high processing performance enables you to easily conduct inspections equivalent to an image processing system. It is optimal for multipoint inspections that would significantly compromise speed when conducted with traditional smart cameras.

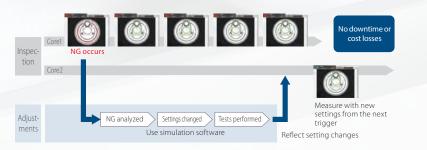


Green : Inspeciton passed, Red : Inspection failed



Settings can be adjusted with zero downtime

Measured values may change gradually due to workpiece variation or changes in external circumstance. Even in such cases, distributed processing across 2 cores allows you to perform cause analysis and setting adjustments as you make measurements. You can eliminate downtime and visual inspection of uninspected items.



\*1. Based on Omron investigation in October 2018.

\*2. Sample comparison to inspection time using vision sensors installed

in customer's machine. Based on Omron investigation in October 2018

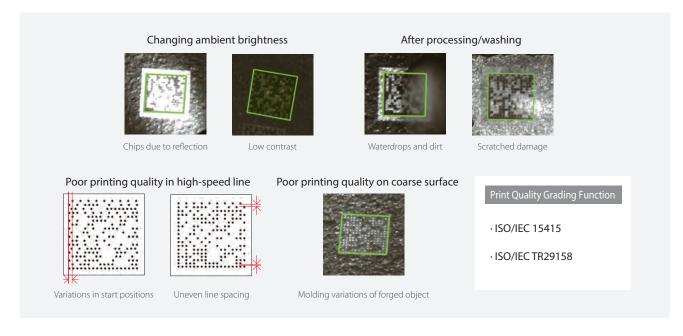
# Traceability and serial number management

The FHV7 Smart Camera is suitable for applications in which inspection results and images are managed by product serial numbers.

# Stable reading regardless of printing quality

#### 2D Code II delivers powerful code reading

The dedicated algorithm for stable 2D code reading under adverse conditions is implemented. Data based on the print quality specifications can be output, which contributes to stable printing.



#### Stable reading of difficult-to-read characters (OCR)

Printed characters can be too close to each other, and characters can be printed on curved surfaces.

Even in these cases, stable reading is possible.



#### Easy installation with built-in dictionary

Many previous character reading methods required dictionary setup before usage, which was a tedious step. The built-in dictionary developed through our long and rich experiences on FA sites includes a variety of fonts and possible character variations, eliminating the need of dictionary setup. You can also add non-conventional characters when special fonts are read.



#### High-speed image storage and image compression

Image data is so large that conventional controllers could not store all images due to limited storage time and storage capacity. The FHV7 Smart Camera has algorithms and hardware that can save images in Omron formats and compress image data at high speed, enabling all images to be stored to meet increasing needs in quality control.



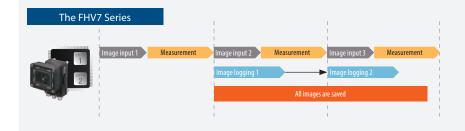
# High-speed image storage

#### Images are saved even during measurements

Distributed processing across 2 cores allows the CPU to perform parallel processing of measurements and image logging. With connection to a high-speed, large-capacity NAS, all images on the high-speed line can be saved, which was previously difficult. \* Trend analysis of all saved images quickly isolates errors and facilitates countermeasures.

- \* All images can be saved under the following conditions:
- One 0.4 Mpix camera
- Measurement time of 30 ms
- JPEG file
- Images can be saved continuously for approx. 380 days when a 3 TB NAS is used (based on 8 hours of operation a day)

For standard smart camera	as				
Priority on measurement Image input 1	Measurement Image inp	out 2 Measurement	Image input 3 Measurement		lssue
processing	measurement	ut 2 Measurement	mage mput s Measurement	1	Since logging was not possible during
Priority on image logging Image input 1	Measurement	Interruption mage input is delayed Image input 2	1 2 Interruption	2	measurement, the user had to choose either measurement or logging. Accordingly, not all images could be saved or image input triggers had to be delayed depending on the measurement trigger intervals.
I	lmage log		Image log	ging z	



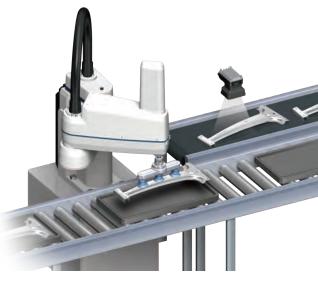
#### Solution

Measurement and image logging are processed in parallel. As a result, you can save all images.

#### Application Examples

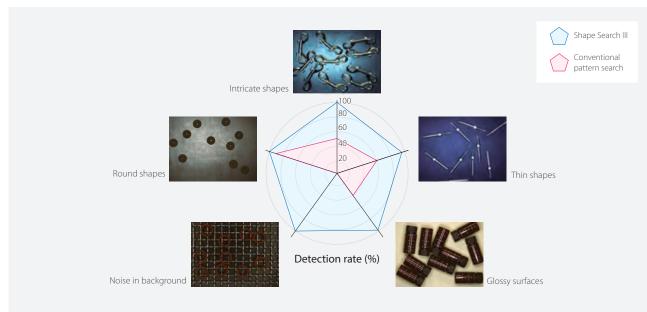
# Pick and place

The FHV7 Smart Camera can be combined with robots for picking and assembling applications.



# Shape Search III stably detects all types of objects

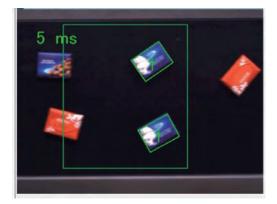
Stable position detection is performed regardless of shape, material, or background.



#### Sorting mixed models

Different types of the searched objects can be sorted.





#### Think & See, Think &See the core technology of Shape Search III

"Think & See" is Omron's powerful core technology for image sensing. Omron is continuously developing technologies to measure, detect, or identify the positions, orientations, shapes, materials, colors, status, or attributes of things, people, vehicles, or other objects faster, more precisely, and more easily than the human eye under various conditions.





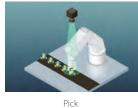
Think & See.

https://www.fa.omron.co.jp/tse

# **OMRON** [ 13

## Easy output to major robot manufacturers' devices

The dialog boxes for the FHV7 Smart Camera and the programs for various vendors' robots greatly reduce the set-up time for robot applications. Refer to the system configuration diagram (p. 16) for connection details.









#### 3-step easy setting

Verified robot communication programs and flowcharts required for robot applications are provided. You don't need to design communications and create a flowchart to set up a robot application.

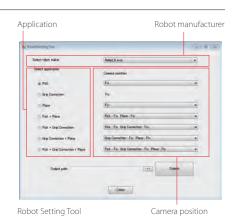
#### STEP 1

Obtain robot program and flowchart

#### Just a few clicks in Robot Setting Tool

Select 3 items to obtain the communication program and flowchart you need.

You can download the Robot Setting Tool from the following URL: http://www.ia.omron.com/fhv



STEP **2** Calibrate

#### Move robot for calibration from the FHV7 Series

The obtained flowchart can be used to move the robot for calibration from the FHV7 Smart Camera. There is no need to create a program for robot calibration.

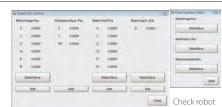


Flowchart Move robot

STEP **3** Check operations

#### Set up and check application from the FHV7 Series

Set the coordinates of the robot and check robot operations using the dialog boxes.



Set the coordinates of the robot

operations

# Product lineup

The product lineup includes general-use Smart Cameras and high-speed, high-accuracy vision systems. You can choose the right one according to your requirements for speed and accuracy of each process. Both FH Series and FHV7 Series have the common user interface and operating procedures, so it is possible to share the same image inspection method across the production line. This reduces the time for operator training. The compatibility of setting data enables you to upgrade hardware easily when speed and accuracy enhancement is needed.

		For various typ Smart Camera FHV7 Series	es of insp	ections	For proce high spee Vision Sys FH Series		ng resolution
					œ.		
		FI	HV7H		FH-205	0	FH-5050
	Performance *1		*		**		***
Herdman	No. of cameras		1		8		8
Hardware Grade	Resolution	<sub>Мріх</sub> 5 (	1.6 <sup>Mpix</sup> 6.3 <sup>Mpix</sup>	3.2 Mpix 12 Mpix	0.3 <sub>Mpix</sub> 5 <sub>Mpix</sub>	0.4 Mpix	2 Mpix 20.4 Mpix
One Software	Screens	Main scree			nent flow screen		eent condition ag screen
	Image logging format		JPEG	BMF	D IF2 (Omron fo		
	Setting data			Compa	tible *2		

\*1.  $\star$ : The more starts, the higher the performance.

<sup>\*2.</sup> Settings for the common functions can be shared between series.

Display Image Hold

# Processing items

Most frequently used processing items come standard, according to customer usage of the high-spec vision system FH Series.

Group	Processing Item	FHV7 Series	FH Series	Group	Processing Item	FHV7 Series	FH Serie
	Search	~	√		Unit Macro	-	~
	Flexible Search	√	√		Unit Calculation Macro	-	~
	Sensitive Search	√	√		Calculation	√	~
	ECM Search	-	√		Line Regression	√	~
	EC Circle Search	-	~		Circle Regression	√	√
	Shape Search II	-	~		Precise Calibration	~	✓
	Shape Search III	√	✓		User Data	-	√
	EC Corner	-	✓		Set Unit Data	-	√
	Ec Cross	-	✓		Get Unit Data	-	√
	Classification	√	~		Set Unit Figure	-	√
	Edge Position	√	✓		Get Unit Figure	-	√
	Edge Pitch	√	√		Trend Monitor	√	√
	Scan Edge Position	~	✓		Image Logging	√	✓
	Scan Edge Width	√	✓		Image Conversion Logging	√	✓
	Circular Scan Edge Position	√			Data Logging	-	
	Circular Scan Edge Width	√	· ·		Elapsed Time	√	
	Intersection	· √	· √		Wait	· ·	· ·
leasurement	Color Data	 √	· √		Focus	-	· ·
		 ✓	✓ ✓	Support	Iris	-	✓ ✓
	Gravity and Area Labeling	✓ ✓	✓ ✓		Parallelize	-	✓ ✓
	Label Data		✓ ✓	measurement	Parallelize Task	 ✓	✓ ✓
		-	✓ ✓			✓ ✓	✓ ✓
	Defect	-			Statistics		
	Precise Defect	✓	✓		Referrence Calib Data	✓	<ul> <li>✓</li> </ul>
	Fine Matching	✓	✓		Position Data Calculation	✓	<ul> <li>✓</li> </ul>
	Character Inspect	√	√		Stage Data	~	√
	Date Verification	~	√		Robot Data	~	√
	Model Dictionary	$\checkmark$	~		Vision Master Calibration	√	√
	2DCode II	√	✓		PLC Mastoer Calibration	-	√
	2DCode	√	~		Convert Position Data	√	✓
	Barcode	✓	~		Movement Single Position	√	✓
	OCR User Dictionary	√	✓		Movement Multi Points	√	✓
	OCR	$\checkmark$	$\checkmark$		Detection Point	-	✓
	Circle Angle	-	✓		Manual Position Setting	-	√
	Glue Bead Inspection	$\checkmark$	$\checkmark$		Camera Calibration	~	√
	Camera Image Input	-	~		Data Save	-	✓
	Camera Image Input FH	-	✓		Conveyor Calibration	-	✓
	Camera Image Input FHV	~	$\checkmark$		Scene	√	✓
	Camera Image Input HDR	-	$\checkmark$		System Information	~	√
	Camera Image Input HDR Lite	-	✓		Conditional Branch	-	✓
iput Image	Photometric Stereo Image Input	-	✓		End	√	✓
	Camera Switch	-	✓		DI Branch	-	√
	Measurement Image Switching	√	√		Control Flow Normal	-	<b>√</b>
	Multi-trigger Imaging	~	√		Control Flow PLC Link	-	✓
	Multi-trigger Imaging Task	~	√		Control Flow Parallel	-	✓
	Position Compensation	√	✓		Control Flow Fieldbus	-	✓
	Filtering	· √	· ·	Branch	Selective Branch	-	· ·
	Backgrond Suppression	· √	· √		Conditional Execution (If)	√	· ·
	Brightness Correct Filter	· √	· √		Conditional Execution (II)	· · · · · · · · · · · · · · · · · · ·	· ·
	Color Gray Filter	√	· ·		Loop	· · ·	· ·
	Extract Color Filter	· √	· · · · · · · · · · · · · · · · · · ·		Loop Suspension	· · · · · · · · · · · · · · · · · · ·	· ·
ompensate	Anti Color Shading	 ✓	✓ ✓		Select Execution(Select)	 ✓	▼ ✓
-	Stripes Removal Filter II	✓ ✓	✓ ✓		Select Execution(Select)	 ✓	▼ ✓
nage	Polar Transformation	✓ ✓	✓ ✓			✓ ✓	✓ ✓
		✓ ✓	✓ ✓		Result Output (I/O)	✓ ✓	✓ ✓
	Trapezoidal Correction				Result Output(Message)		✓ ✓
	Machine Simulator	-	✓	Output result	Data Output	-	
	Image Subtraction	✓	✓		Parallel Data Output	-	<ul> <li>✓</li> </ul>
	Advanced filter	~	✓		Parallel Judgement Output	-	<ul> <li>✓</li> </ul>
	Panorama	-	$\checkmark$		Fieldbus Data Output	-	<ul> <li>✓</li> </ul>
					Result Display	√	<ul> <li>✓</li> </ul>
					Display Image File	-	~
				Display result	Display Last NG Image	√	√
					Conveyor Panorama Display	-	~
					Display Image Hold	✓	1

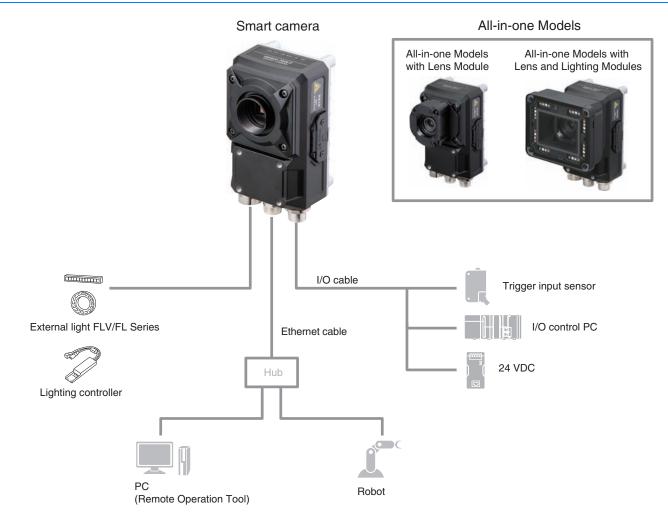
# Smart Camera FHV7 Series

# The functionality and speed that your production site demands packed in an all-in-one device

- A robust all-in-one body that makes it easy to install
- Flexibly accommodates object changes
- Excellent productivity performance



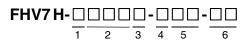
# **System Configuration**



#### **Model Number Structure**

#### FHV7 Series Model Number Legend

Use this legend when determining the product specifications from the model number. When ordering, use a model number from the table in *Ordering Information*.



No.	Classification	Code	Meaning
1	Imaga aanaara	М	Monochrome
I	Image sensors	С	Color
		004	400,000 pixels
		016	1.6 million pixels
2	Resolution	032	3.2 million pixels
2		050	5 million pixels
		063	6.3 million pixels
		120	12 million pixels
3	Shutter type	-	Global shutter
3	Shutter type	R	Rolling shutter
4	Lens	С	C mount
4	Lens	S	Autofocus Lens

No.	Classification	Code	Meaning
		06	6 mm
		09	9 mm
5	Focal length	12	12 mm
		16	16 mm
		25	25 mm
	Light color	R	Red
6		W	White
0		IR	IR
		MC	Multi color

# Configuration

For the Smart Camera FHV7 series, there are five configurations below by module combinations.

Smart	t camera	Lens	Internal lighting	Protective structure	Integrated model	Appearance	Configuration
400,000 pixels 1.6 million pixels 3.2 million pixels	FHV7H004 FHV7H016 FHV7H032	C mount lens 3Z4SLE	N/A	IP40	FHV7HC		C mount lens/IP40
5 million pixels 6.3 million pixels 12 million pixels	FHV7H-050- FHV7H-063R- FHV7H-120R-	-050-0 3Z4SLE		IP67 Waterproof Hoods required FHV-XHD-S FHV-XHD-L	N/A	ব্	C mount lens/IP67
			N/A	IP40	FHV7H		Lens module/IP40
1.6 million pixelsFHV7H-016-03.2 million pixelsFHV7H-032-0	FHV7H004 FHV7H016 FHV7H032 FHV7H063R	V7H-004-0 V7H-016-0 FHV lens module V7H-0032-0 FHV-LEM-S0 V7H-063R-0		IP67 Waterproof Hoods required FHV-XHD-LEM	N/A	Ŵ	Lens module/IP67
			FHV-LTM-🗆	IP67	FHV7H S	Q	Lens module /Internal lighing - IP67

#### **Model Selection**

To select a model of Smart Camera, use the WEB Selector.

http://www.ia.omron.com/fhv\_select\_e

Note: With certain module types, the operation of some combinations cannot be guaranteed.

Use the Web Selector to select the correct combination of image sensor, lens, resolution, and light.

# **Ordering Information**

#### Smart Cameras C Mount Models

Item	Resolution	Model		
nem	Resolution	Color	Monochrome	
	400,000 pixels	FHV7H-C004-C	FHV7H-M004-C	
	1.6 million pixels	FHV7H-C016-C	FHV7H-M016-C	
	3.2 million pixels	FHV7H-C032-C	FHV7H-M032-C	
	5 million pixels	FHV7H-C050-C	FHV7H-M050-C	
	6.3 million pixels	FHV7H-C063R-C	FHV7H-M063R-C	
	12 million pixels	FHV7H-C120R-C	FHV7H-M120R-C	

#### All-in-one Models with Lens Module

	Deschution	1	Es est la sette		Model
Item	Resolution	Lens	Focal length	Color	Monochrome
			6 mm	FHV7H-C004-S06	FHV7H-M004-S06
			9 mm	FHV7H-C004-S09	FHV7H-M004-S09
	400,000 pixels	Autofocus Lens	12 mm	FHV7H-C004-S12	FHV7H-M004-S12
			16 mm	FHV7H-C004-S16	FHV7H-M004-S16
			25 mm	FHV7H-C004-S25	FHV7H-M004-S25
			6 mm	FHV7H-C016-S06	FHV7H-M016-S06
			9 mm	FHV7H-C016-S09	FHV7H-M016-S09
and the second s	1.6 million pixels	Autofocus Lens	12 mm	FHV7H-C016-S12	FHV7H-M016-S12
0			16 mm	FHV7H-C016-S16	FHV7H-M016-S16
			25 mm	FHV7H-C016-S25	FHV7H-M016-S25
Tree L			6 mm	FHV7H-C032-S06	FHV7H-M032-S06
			9 mm	FHV7H-C032-S09	FHV7H-M032-S09
and the second s	3.2 million pixels	Autofocus Lens	12 mm	FHV7H-C032-S12	FHV7H-M032-S12
			16 mm	FHV7H-C032-S16	FHV7H-M032-S16
			25 mm	FHV7H-C032-S25	FHV7H-M032-S25
			6 mm	FHV7H-C063R-S06	FHV7H-M063R-S06
			9 mm	FHV7H-C063R-S09	FHV7H-M063R-S09
	6.3 million pixels	Autofocus Lens	12 mm	FHV7H-C063R-S12	FHV7H-M063R-S12
			16 mm	FHV7H-C063R-S16	FHV7H-M063R-S16
			25 mm	FHV7H-C063R-S25	FHV7H-M063R-S25

Item	Resolution Lens Focal length Light c		Light color	М	Model	
nem	nesolution	Lens	Focal length	Light color	Color	Monochrome
				Multi color	FHV7H-C004-S06-MC	FHV7H-M004-S06-M
			6 mm	Red		FHV7H-M004-S06-R
			0 1111	White	FHV7H-C004-S06-W	FHV7H-M004-S06-W
				IR		FHV7H-M004-S06-IR
				Multi color	FHV7H-C004-S09-MC	FHV7H-M004-S09-M
			9 mm	Red		FHV7H-M004-S09-R
			0 11111	White	FHV7H-C004-S09-W	FHV7H-M004-S09-W
				IR		FHV7H-M004-S09-IR
				Multi color	FHV7H-C004-S12-MC	FHV7H-M004-S12-M
	400,000 pixels	Autofocus Lens	12 mm	Red		FHV7H-M004-S12-R
	400,000 pixels	Autolocus Echs	12 11111	White	FHV7H-C004-S12-W	FHV7H-M004-S12-W
				IR		FHV7H-M004-S12-IR
				Multi color	FHV7H-C004-S16-MC	FHV7H-M004-S16-M
			16 mm	Red		FHV7H-M004-S16-R
			10 mm	White	FHV7H-C004-S16-W	FHV7H-M004-S16-W
				IR		FHV7H-M004-S16-IR
				Multi color	FHV7H-C004-S25-MC	FHV7H-M004-S25-M
			25 mm	Red		FHV7H-M004-S25-R
			25 1111	White	FHV7H-C004-S25-W	FHV7H-M004-S25-W
				IR		FHV7H-M004-S25-IR
				Multi color	FHV7H-C016-S06-MC	FHV7H-M016-S06-M
			6 mm	Red		FHV7H-M016-S06-R
				White	FHV7H-C016-S06-W	FHV7H-M016-S06-W
				IR		FHV7H-M016-S06-IR
			9 mm	Multi color	FHV7H-C016-S09-MC	FHV7H-M016-S09-M
				Red		FHV7H-M016-S09-R
				White	FHV7H-C016-S09-W	FHV7H-M016-S09-W
				IR		FHV7H-M016-S09-IR
-BE				Multi color	FHV7H-C016-S12-MC	FHV7H-M016-S12-M
	1.0	A	10	Red		FHV7H-M016-S12-R
	1.6 million pixels	Autofocus Lens	12 mm	White	FHV7H-C016-S12-W	FHV7H-M016-S12-W
				IR		FHV7H-M016-S12-IR
				Multi color	FHV7H-C016-S16-MC	FHV7H-M016-S16-M
			10	Red		FHV7H-M016-S16-R
			16 mm	White	FHV7H-C016-S16-W	FHV7H-M016-S16-W
				IR		FHV7H-M016-S16-IR
				Multi color	FHV7H-C016-S25-MC	FHV7H-M016-S25-M
				Red		FHV7H-M016-S25-R
			25 mm	White	FHV7H-C016-S25-W	FHV7H-M016-S25-W
				IR		FHV7H-M016-S25-IR
				Multi color	FHV7H-C032-S06-MC	FHV7H-M032-S06-M
				Red		FHV7H-M032-S06-R
			6 mm	White	FHV7H-C032-S06-W	FHV7H-M032-S06-W
				IR		FHV7H-M032-S06-IR
				Multi color	FHV7H-C032-S09-MC	FHV7H-M032-S09-M
				Red		FHV7H-M032-S09-R
	3.2 million pixels	Autofocus Lens	9 mm	White	FHV7H-C032-S09-W	FHV7H-M032-S09-W
				IR		FHV7H-M032-S09-IR
				Multi color	FHV7H-C032-S12-MC	FHV7H-M032-S12-M
				Red		FHV7H-M032-S12-M
			12 mm		 EUV7U_C022_612_W	
			12 11111	White	FHV7H-C032-S12-W	FHV7H-M032-S12-W

ltem	Resolution	Lana		Linht color:	Мо	del
Item	Resolution Lens Focal length Light col	Light color	Color	Monochrome		
				Multi color	FHV7H-C032-S16-MC	FHV7H-M032-S16-MC
			10	Red		FHV7H-M032-S16-R
			16 mm	White	FHV7H-C032-S16-W	FHV7H-M032-S16-W
	0.0 million nivele	Autofocus Lens		IR		FHV7H-M032-S16-IR
	3.2 million pixels	Autorocus Lens		Multi color	FHV7H-C032-S25-MC	FHV7H-M032-S25-MC
			25 mm	Red		FHV7H-M032-S25-R
			25 mm	White	FHV7H-C032-S25-W	FHV7H-M032-S25-W
				IR		FHV7H-M032-S25-IR
				Multi color	FHV7H-C063R-S06-MC	FHV7H-M063R-S06-MC
			6 mm	Red		FHV7H-M063R-S06-R
			0 1111	White	FHV7H-C063R-S06-W	FHV7H-M063R-S06-W
				IR		FHV7H-M063R-S06-IR
			9 mm	Multi color	FHV7H-C063R-S09-MC	FHV7H-M063R-S09-MC
The second s				Red		FHV7H-M063R-S09-R
			91111	White	FHV7H-C063R-S09-W	FHV7H-M063R-S09-W
				IR		FHV7H-M063R-S09-IR
				Multi color	FHV7H-C063R-S12-MC	FHV7H-M063R-S12-MC
	6.3 million pixels	Autofocus Lens	12 mm	Red		FHV7H-M063R-S12-R
	6.5 million pixels	Autolocus Leris	12 11111	White	FHV7H-C063R-S12-W	FHV7H-M063R-S12-W
				IR		FHV7H-M063R-S12-IR
				Multi color	FHV7H-C063R-S16-MC	FHV7H-M063R-S16-MC
			16 mm	Red		FHV7H-M063R-S16-R
			10 11111	White	FHV7H-C063R-S16-W	FHV7H-M063R-S16-W
				IR		FHV7H-M063R-S16-IR
				Multi color	FHV7H-C063R-S25-MC	FHV7H-M063R-S25-MC
			25 mm	Red		FHV7H-M063R-S25-R
			20 11111	White	FHV7H-C063R-S25-W	FHV7H-M063R-S25-W
				IR		FHV7H-M063R-S25-IR

#### **Lens Modules**

Item	Item		Model
		6 mm	FHV-LEM-S06
		9 mm	FHV-LEM-S09
	Autofocus Lens	12 mm	FHV-LEM-S12
		16 mm	FHV-LEM-S16
Ent		25 mm	FHV-LEM-S25

Refer to the *Vision Accessory Catalog* (Cat No. Q198) for details on C-mount lenses.

# **Lighting Modules**

Item	Light color	Model
	Multi color	FHV-LTM-MC
	Red	FHV-LTM-R
0	White	FHV-LTM-W
	IR	FHV-LTM-IR

#### **Optical Filters**

tem		Model
Polarized Light Filter	For visible light	FHV-XPL
Polarized Light Filter	For both infrared light and visible light	FHV-XPL-IR
Diffusion Filter		FHV-XDF

Waterproof Hoods Required to ensure IP67 protection without using a lighting module.

Item	Model				
Waterproof Hood for Lens Modules	FHV-XHD-LEM				
Waterproof Hood for C-mount Lens (Short) *1					
Waterproof Hood for C-mount Lens (Long) *2	FHV-XHD-L				

\*1. Can be used with the following lenses. 3Z4S-LE SV-0614V, 3Z4S-LE SV-0813V, 3Z4S-LE SV-1214V, 3Z4S-LE SV-1614V, 3Z4S-LE SV-2514V

\*2. Can be used with the following lenses. 3Z4S-LE SV-0614H, 3Z4S-LE SV-0814H, 3Z4S-LE SV-1214H, 3Z4S-LE SV-1614H, 3Z4S-LE SV-2514H, 3Z4S-LE SV-3514H, 3Z4S-LE SV-5014H

#### Cables

	Item	Cable length	Model
		2 m	FHV-VDB 2M
		3 m	FHV-VDB 3M
	I/O Cable (Bend Resistant)	5 m	FHV-VDB 5M
		10 m	FHV-VDB 10M
1		20 m	FHV-VDB 20M
		2 m	FHV-VDLB 2M
		3 m	FHV-VDLB 3M
	I/O Cable (Bend Resistant, Right-angle)	5 m	FHV-VDLB 5M
		10 m	FHV-VDLB 10M
1		20 m	FHV-VDLB 20M
6		2 m	FHV-VNB 2M
		3 m	FHV-VNB 3M
	Ethernet Cable (Bend Resistant)	5 m	FHV-VNB 5M
		10 m	FHV-VNB 10M
		20 m	FHV-VNB 20M
		2 m	FHV-VNLB 2M
		3 m	FHV-VNLB 3M
	Ethernet Cable (Bend Resistant, Right-angle)	5 m	FHV-VNLB 5M
		10 m	FHV-VNLB 10M
9		20 m	FHV-VNLB 20M

#### Accessories

	Item		Model			
	Base Mount for Smart Cameras and Lighting C	Base Mount for Smart Cameras and Lighting Controllers				
	Base Mount for Lighting Controllers	Base Mount for Lighting Controllers				
	Light Cover (for replacement) *1	Light Cover (for replacement) *1				
Ś	Waterproof Cap (for replacement)	for Ethernet Connecter	FHV-XWC-ECN			
		for Light Connecter	FHV-XWC-LCN			
		for Camera	FHV-XWP-CAM			
	Waterproof Packing *2 (for replacement, 5 pcs)	for Lighting Module	FHV-XWP-LTM			
$\bigcirc$		for Waterproof Hood	FHV-XWP-HD-SL			
	FHV-XLS-LTM					

\*1. Adapted lighting module FHV-LTM-W, FHV-LTM-R, FHV-LTM-IR, FHV-LTM-MC
 \*2. Always replace when a module is removed.

#### Accessories

Item		Descriptions				
-	Industrial Switching Hubs	3 port	Failure detection: None	Current consumption: 0.08 A	W4S1-03B	
18	for EtherNet/IP and Ether- net	5 port	Failure detection: None	Current consumption:	W4S1-05B	
		5 port	Failure detection: Supported	0.12 A	W4S1-05C	

#### Lenses

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

			Recommended lens				
Resolution	Camera Model	Size of image element	Standard Lens	Telecentric Lens	Vibrations and Shocks Resistant Lens		
400,000-pixel	FHV7H-004	1/2.9" equivalent	SV-V Series				
1.6 million-pixel	FHV7H-016	1/2.9" equivalent	SV-V Series		VS-MCA Series		
3.2 million-pixel	FHV7H-032	1/1.8" equivalent		VS-TCH Series			
5 million-pixel	FHV7H-060	2/3" equivalent	SV-H Series	VS-TCH Series	Non-telecentric Macro VS-MC Series		
6.3 million-pixel	FHV7H-D063R	1/1.8" equivalent					
12 million-pixel	FHV7H-[]120R	1/1.7" equivalent					

# **Ratings and Specifications**

#### **Smart Camera**

Item		Model	FHV7H- M004-C	FHV7H- C004-C	FHV7H- M016-C	FHV7H- C016-C	FHV7H- M032-C	FHV7H- C032-C	FHV7H- M050-C	FHV7H- C050-C	FHV7H- M063R-C	FHV7H- C063R-C	FHV7H- M120R-C	FHV7H- C120R-C
		Standard	Yes											
	Operation Mode	Double speed multi-input	Yes											
	mode	Non-stop adjustment mode	Yes											
	Parallel pr	ocessing	Yes											
Specifica tions			256		64		36		25		19		10	
	Possible N logging im Smart Can	ages to	214		52		25		15		12		5	
	Possible N	lo. of scenes	128 *1											
	UI operatio	on	Remote 0	Operation 7	Fool									
	Setup			•	ng flow usi	-	-							
	Language		-				1		erman, Fre	ench, Italia	1			-
	CMOS Ima	ge elements	1/2.9-inch equivaler		1/2.9-incl equivaler		1/1.8-incl equivaler		2/3-inch e	equivalent	1/1.8-inch equivaler		1/1.7-inch equivalen	
	Color/Mon	ochrome	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color
-	Effective p	ixels (H x V)	720 × 540	0	1440 × 1	080	2048 × 1	536	2448 × 20	)48	3072 × 20	048	$4000 \times 30$	000
	Pixel size		$6.9 \times 6.9$	μm	3.45 × 3.4	45 µm	3.45 × 3.4	45 µm	3.45 × 3.4	15 µm	$2.4 \times 2.4$	μm	1.85 × 1.8	35 µm
	Imaging area H × V (opposing corner)		5.0 × 3.8	(6.3 mm)	5.0 × 3.8	(6.3 mm)	7.1 × 5.3	(8.9 mm)	8.5 × 7.1	(11.1 mm)	7.4 × 5.0	(8.9 mm)	7.4 × 5.6	(9.3 mm)
	Shutter system		Global Sh	nutter							Rolling sh (Global re		compatible	)
Imaging	Shutter fu	nction	Electronic	Electronic shutter: Shutter speed can be set from 1 $\mu s$ to 100 ms.					Electronic Shutter s be set fro to 100 ms	peed can m 55 µs	Electronic Shutter sp be set fro to 100 ms	beed can m 84 μs		
	Partial fun	ction	4 to 540 l (4-line inc	ines crements)	4 to 1080 (4-line ind	lines crements)	4 to 1536 (4-line inc		4 to 2048 (4-line inc		4 to 2048 (4-line inc	lines crements)	4 to 3000 (4-line inc	
	Frame rate acquisition		430 fps (2	2.3 ms)	224 fps (4	4.5 ms)	55 fps (18	3.0 ms)	35 fps (28	3.0 ms)	59 fps (16	6.7 ms)	19 fps (25	5.0 ms)
	Lens mou	nting	C mount										1	
	Field of vie Installation		Selecting	a lens acc	ording to t	he field of	view and ir	stallation	distance					
	Serial		RS-232C	× 1										
	Ethernet			Non-proce BASE-T ×	dure (TCP 1	/UDP)								
	EtherNet/I	P	Yes (Tarç	get/Etherne	et port)									
	PROFINET	•	Yes (Slav	e/Etherne	t port), Cor	nformance	class A							
External Interface	Parallel I/C	)	NPN/PNF	o common										
Parallel I/F				ed input: 1	, General i	nput: 3, Hig	gh-speed c	utput: 1, G	ieneral out	out: 4				
	Encoder I/		N/A											
	Monitor I/F			N/A										
	USB I/F SD Card I/	-												
SD Card I/F         microSD card: SDHC × 1           Main         PWR: Green, RUN: Green, LINK: Yellow, BUSY: Green, OR: Yellow, ERR: Red														
Indicator I	Lamps	SD		ESS: Yellov	,	VIX. TEHOW	, 503 î. G	een, Un:	i ellow, ER	n. neu				
Supply Vo	oltage	55				an I/O cat	le with 20	m is conne	cted, it is 2	4.0 VDC #	0 26.4 VDC	2.)		
,	•										0.1 100	/		
Current Consumption With lighting modules: 4.2 A Without lighting modules: 0.60 A														

**\*1.** The number of scenes can be increased up to 1,024 with the Conversion scene group data tool.

Item	Model	FHV7H- M004-C	FHV7H- C004-C	FHV7H- M016-C	FHV7H- C016-C	FHV7H- M032-C	FHV7H- C032-C	FHV7H- M050-C	FHV7H- C050-C	FHV7H- M063R-C	FHV7H- C063R-C	FHV7H- M120R-C	FHV7H- C120R-C
	Ambient temperature range	Operating	g: 0 to +40	°C, Storage	e: -25 to +6	5°C (with	no icing or	condensat	tion)				
	Ambient humidity range	Operating	rating & Storage: 35 to 85%RH (With no condensation)										
	Ambient atmosphere	No corros	sive gases										
Vibration tolerance         Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 With lens modules: Half amplitude: 0.15 mm (Others are the same as above.)													
Environ ment	Shock resistance	Impact fo	rce: 150 m	/s², Test d	irection: 6	directions,	three time	each (up/c	lown, front	/behind, let	it/right)		
	Noise immunity	<ul> <li>Fast transient burst</li> <li>DC power Direct infusion: 2kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 300 Application time: 1 min.</li> <li>I/O line Direct infusion: 1kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 300 Application time: 1 min.</li> </ul>											
	Grounding	Class D g	grounding (	100 $\Omega$ or l	ess ground	ing resista	nce) <b>*</b> 2						
	Dimensions	110 mm :	× 68.5 mm	× 55.5 mn	n (H × W ×	D)							
	Weight	Approx. 6	670 g										
External shape	Degree of protection	(except a	ing module connector n the abov	cap remov		s: IEC605	29 - IP67						
	Case material	Aluminun	n die-castir	ng (ADC12	)								
Accessori	ies	Aluminum die-casting (ADC12)   Connector cap for Ethernet cable (mounted on the body): 1  Connector cap for an external lighting (mounted on the body): 1  C mount cap (mounted on the body): 1  C mount cover (mounted on the body): 1  Instruction sheet: 1  Membership registration: 1  Compliance sheet: 1											

\*2. Existing the third class grounding

#### **Lens Modules**

Item		FHV-LEMS06	FHV-LEMS09	FHV-LEMS12	FHV-LEMS16	FHV-LEMS25			
Focal length		6 mm	9 mm	12 mm	16 mm	25 mm			
Installation dist	ance	59 to 1000 mm	60 to 1000 mm	60 to 1000 mm	110 to 2000 mm	188 to 2000 mm			
	Ambient temperature range	Operating: 0 to +40°C	, Storage: -25 to +65°	C (with no icing or cond	lensation)				
	Ambient humidity range	Operating & Storage:	35 to 85%RH (With no	condensation)					
Usage	Ambient atmosphere	No corrosive gases							
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.15 mm <b>*</b> , Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10							
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)							
	Dimension	50 mm × 41 mm × 31 mm (H × W × D)							
External shape	Weight	Approx. 50 g							
	Case material	Polycarbonate							
Accessories		<ul> <li>Special cover for F</li> <li>Screws: M3 × 8 mr</li> <li>Instruction sheet :</li> <li>Compliance sheet:</li> </ul>	m: 5 (including one spa 1	re piece)					

\*When the lens module is mounted to the product, the specifications of vibration tolerance are changed.

#### **Lighting Modules**

Model		FHV-LTM-W	FHV-LTM-R	FHV-LTM-IR	FHV-LTM-MC				
Color		White	Red	Infrared light	Multi color				
Peak wave len	gth	-	Typ. 630 nm	Typ. 850 nm	R: Typ. 630 nm G: Typ. 525 nm B: Typ. 465 nm IR: Typ. 850 nm				
Light source		LED	LED	LED	LED				
Risk group		Group 2	Group 1	Group 1	R: Group 1 G: Group 2 B: Group 2 IR: Group 1				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)							
Jsage	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)							
	Ambient atmosphere	No corrosive gases							
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10							
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)							
Dimensions		52 mm × 91 mm × 77 mm	$(H \times W \times D)$						
Weight		270 g	270 g	270 g	270 g				
Material		Aluminum die-casting (ADC12), polycarbonate							
Accessories		Waterproof packing (sm Waterproof packing (lar Light shielding sheet FH Lighting cover FHV-XC' Hexagonal wrench (leng Instruction sheet: 1 Compliance sheet: 1	ge) FHV-XWP-LTM: 1 IV-XLS-LTM: 1 V: 1						

# **Optical Filters**

Model		FHV-XDF	FHV-XPL	FHV-XPL-IR			
Filter type		Diffusion filter Polarization filter		Polarization filter			
Wavelength		Visible to infrared	Visible	Visible to infrared			
Adapted lightin	ig module	FHV-LTM-W FHV-LTM-R FHV-LTM-IR FHV-LTM-MC	FHV-LTM-W FHV-LTM-R FHV-LTM-IR FHV-LTM-MC				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)					
Usage	Vibration tolerance	No corrosive gases					
environment	Shock resistance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10					
	Vibration tolerance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)					
Material		Aluminum (A6061), polycarbonate					
Weight		Approx. 70 g	Approx. 70 g	Approx. 70 g			

#### Waterproof Hoods

Model		FHV-XHD-S	FHV-XHD-L	FHV-XHD-LEM			
Suitable lens		3Z4S-LE SV-V series SV-0614V SV-0813V SV-1214V SV-1614V SV-2514V	3Z4S-LE SV-H series SV-0614H *1 SV-0814H *2 SV-1214H SV-1614H SV-2514H SV-3514H SV-3514H	FHV-LEM-S series FHV-LEM-S06 FHV-LEM-S09 FHV-LEM-S12 FHV-LEM-S16 FHV-LEM-S25			
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)					
Usage	Ambient atmosphere	No corrosive gases					
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10					
	Shock resistance	n: 6 directions, three time each (up/do	wn, front/behind, left/right)				
Material	·	Aluminum (A6061), polycarbonate					
Weight		Approx. 220 g	Approx. 220 g	Approx. 220 g			

**\*1.** This is not available in FHV7H-\_050, FHV7H-\_063R, FHV7H-\_120R. **\*2.** This is not available in FHV7H-\_050.

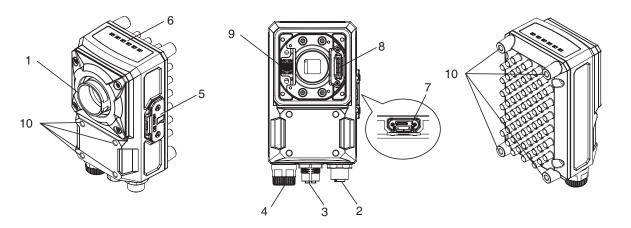
#### I/O cables

Item		FHV-VDB 2M		FHV-VDB 3M		FHV-VDB 5M		FHV-VDB 10M		FHV-VDB 20M		
Cable length		2 m		3 m		5 m		10 m		20 m		
Cable type		Bending res	Bending resistance cable									
Connector type		Straight connector	Right angle connector	Straight connector	Right angle connector	Straight connector	Rightangle connector	Straight connector	Right angle connector	Straight connector	Right angle connector	
0:	Power line	AWG21										
Size	Others	AWG26										
Outer diameter		9.0±0.3 mm dia.										
Min. bending radius		Fixed use: 54 mm, Sliding use: 72 mm										
Usage environment	Ambient temperature range	Operating: -30 to +80°C, Storage: -30 to +100°C (with no icing or condensation)										
	Ambient humidity range	Operating & Storage: 0 to 93%RH (With no condensation)										
	Ambient atmosphere	No corrosive gases										
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10										
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)										
Material		Mold part: Nylon, Thermoplastic polyurethane, Sheath part: PVC										
Weight		Approx. 270	Оg	Approx. 39	Эg	Approx. 620	) g	Approx. 12	00 g	Approx. 23	50 g	

#### **Ethernet Cables**

Item		FHV-VNB 2M		FHV-VNB 3M		FHV-VNB 5M		FHV-VNB 10M		FHV-VNB 20M	
Cable length		2 m		3 m		5 m		10 m		20 m	
Cable type		Bending res	sistance cabl	e							
Connector type		Straight connector	Right angle connector	Straight connector	Right angle connector	Straight connector	Rightangle connector	Straight connector	Right angle connector	Straight connector	Right angle connector
Outer diameter		7.2+0.3 mm dia.									
Min. bending radius		Fixed use: 35 mm, Sliding use: 70 mm									
	Ambient temperature range	Operating: -40 to +80°C, Storage: -40 to +100°C (with no icing or condensation)									
	Ambient humidity range	Operating & Storage: 0 to 93%RH (With no condensation)									
Usage environment	Ambient atmosphere	No corrosive gases									
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10									
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material		Mold part: Nylon, Thermoplastic polyurethane, Sheath part: Polyurethane									
Weight		Approx. 210	) g	Approx. 240	) g	Approx. 310	) g	Approx. 380	) g	Approx. 73	) g

# Parts and Names



No.		Name Description						
1	Imaging unit		Captures images.					
2	Connector for I/O cab	le	Use this connector when connecting the smart camera with a power supply or an external device using an I/O cable. Dedicated I/O cable: FHV-VD					
3	Connector for Etherne	et cable	Use this connector when connecting the smart camera with a personal compute and so on using an Ethernet cable. Dedicated Ethernet cable: FHV-VN					
4	Connector for externa	al lighting	Use this connector when connecting an external lighting and the external lighting controller. Connectable external lighting controller: FL-TCC and FLVTCC					
5	Connector to attach n	nicroSD card	Use this connector to attach a microSD card. Do not extract/insert the microSD card during processing. Otherwise, measurement time may be influenced or data may be broken.					
		PWR (Green)	Lights while power is supplied.					
		RUN (Green)	Lights when switching to the layout in which the RUN signal output is set ON.					
6		LINK (Yellow)	Lights when connected with Ethernet equipment and blinks during communication.					
	Operation indicator	BUSY (Green)	Lights while processing is in progress.					
		OR (Yellow)	Lights when the overall judgment output signal is ON.					
		ERR (Red)	Lights when an error occurs.					
7		SD ACCESS (Yellow)	Lights when accessing to the microSD card.					
8	Connector for lighting	module (White)	Use this connector when mounting the lighting module.					
9	Connector for lens me	odule (Black)	Use this connector when mounting the lens module.					
10	Mounting screw holes	3	Use them to screw up the smart camera. Recommended tightening torque: 2.3N·m					

#### **Processing Items**

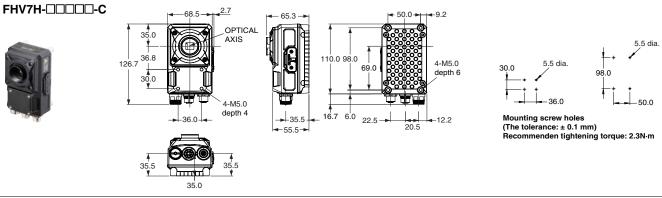
Group	lcon		Processing Item	Group	lcon		Processing Item
	à	Search	Used to identify the shapes and calculate the position of measurement objects.		ABC	Calculation	Used when using the judge results and measured values of ProcItem which are registered in processing units.
-	6000	Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.		*]+	Line Regression	Used for calculating regression line from plural mea- surement coodinate.
	***	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.		O	Circle Regression	Used for calculating regression circle from plural mea- surement coordinate.
		Shape Search III	Robust detection of positions is possible at high-speed and with high precision incorporating environmental fluctuations, such as differences in individual shapes of the workpieces,	-	<b>G</b>	Precise Calibration	Used for calibration corresponding to trapezoidal dis- tortion and lens distortion.
	7	Classification	pose fluctuations, noise superimposition and shielding. Used when various kinds of products on the assembly			Trend Monitor	Used for displaying the information about results on the monitor, facilitating to avoid NG and analyze causes.
		Edge Position	line need to be sorted and identified. Measure position of measurement objects according		<b>2</b> 5	Image Logging	Used for saving the measurement images to the mem- ory and USB memory.
-		Edge Pitch	to the color change in measurement area. Detect edges by color change in measurement area.		<b>≥</b> →	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.
-		Scan Edge	Used for calculating number of pins of IC and connectors. Measure peak/bottom edge position of workpieces accord-		<b>\$</b>	Elapsed Time	Used for calculating the elapsed time since the mea- surement trigger input.
-	*	Position Scan Edge	ing to the color change in separated measurement area. Measure max/min/average width of workpieces ac-		X	Wait	Processing is stopped only at the set time. The stand- by time is set by the unit of [ms].
-	<u>স</u> ্থান্থ	Width Circular Scan	cording to the color change in separated measure- ment area. Measure center axis, diameter and radius of circular			Parallelize	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed at the top of processing to be performed in parallel.
-	<u> </u>	Edge Position Circular Scan	workpieces. Measure center axis, width and thickness of ring work-				A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the
-		Edge Width Intersection	pieces. Calculate approximate lines from the edge information on two sides of a square workpiece to measure the an-			Parallelize Task	measurement time. This processing item is placed im- mediately before processing to be performed in paral- lel between Parallelize and Parallelize End.
Measurement		Color Data	gle formed at the intersection of the two lines. Used for detecting presence and mixed varieties of	Support measurement		Statistics	Used when you need to calculate an average of multiple measurement results.
_		Gravity and Area	products by using color average and deviation. Used to measure area, center of gravity of workpices by extracting the color to be measured.			Referrence Calib Data	Calibration data and distortion compensation data held under other processing items can be referenced.
-		Labeling	Used to measure number, area and gravity of work- pieces by extracting registered color.			Position Data Calculation	The specified position angle is calculated from the measured positions.
_		Precise Defect	Check the defect on the object. Parameters for extrac- tion defect can be set precisely.		<u>+/</u>	Stage Data	Sets and stores data related to stages.
-		Fine Matching	Difference can be detected by overlapping and compar- ing (matching) registered fine images with input images.		<b>4</b> 0	Robot Data	Sets and stores data related to robots. This processing item automatically calculates the en-
-	AB	Character Inspect	Recognize character according correlation search with model image registered in [Model Dictionary].		4	Vision Master Calibration	tire axis movement amount of the control equipment necessary for calibration.
	Date 08-02-1	Date Verification	Reading character string is verified with internal date.		ţ	Convert Position Data	The position angle after the specified axis movement is calculated.
	A	Model Dictionary	Register character pattern as dictionary. The pattern is used in [Character Inspection].			Movement Single Position	The axis movement that is required to match the mea- sured position angle to the reference position angle is calculated.
-		2DCode II *1	Recognize 2D code and display where the code qual- ity is poor.			Movement Multi Points	The axis movements that are required to match the measured position angles to the corresponding refer-
		2DCode *2	Recognize 2D code and display where the code qual- ity is poor.		<u>+1+</u>	Camera	ence position angles are calculated. By setting the camera calibration, the measurement
		Barcode *3	Recognize barcode, verify and output decoded char- acters.		¥.	Calibration	result can be converted and output as actual dimensions.
_	OCR	OCR	Recognize and read characters in images as charac- ter information.			Scene	The specified scene is copied to the current scene. Obtain system information (e.g., memory and disk
-	OCR	OCR User Dictionary	Register dictionary data to use for OCR.		Q	System Information	space and I/O input signal status) of the Sensor Con- troller.
		Glue Bead Inspection	You can inspect coating of a specified color for gaps or runoffs along the coating path.		\$ <u></u>	End	This ProcItem must be set up as the last processing unit of a branch.
-		Camera Image Input FHV Measurement	To input images from cameras. And set up the condi- tions to input images from cameras. (For FHV only) To switch the images used for measurement. Not input		h	Conditional Execution (If)	The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.
Input Image	ut Image Multi-trigger T Imaging Pp	images from camera again. The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert the Multi-		h	Conditional Execution (Else)	Insert between the Conditional Execution (If) process- ing item and End If processing item. The measurement flow is divided according to the comparison result ob- tained using the set expressions and conditions.	
-		Multi-trigger	trigger Imaging to the top of the flow. The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel mea-	Branch	67	Loop	The set processes are repeated until the loop count reaches the specified number, and then the next process starts.
		Imaging Task Position	surement for each image. Insert this processing item to the top of the processing which requires imaging for multiple times. Used when positions are differed. Correct measurement		\$	Loop Suspension	Insert between the Loop processing item and End Loop processing item. Used to stop the loop before the loop count reaches the specified number.
-	<b>1</b>	Compensation	is performed by correcting position of input images. Used for processing images input from cameras in or-		Ψ	Select Execution (Select)	Used to set conditions. The measurement flow is divid- ed according to the comparison result obtained using the conditions given by expressions.
		Backgrond Suppression	der to make them easier to be measured. To enhance contrast of images by extracting color in specified brightness.		st.	Select Execution (Case)	Used to make a judgment. The measurement flow is divided according to the comparison result obtained
-		Brightness Correct Filter	Track brightness change of entire screen and remove gradual brightness change such as uneven brightness.			Result Output (I/	using the conditions given by expressions. Output data to the external devices such as a pro- grammable controller or a PC via PLC Link, Parallel in-
Compensate mage		Color Gray Filter	Color image is converted into monochrome images to emphasize specific color.		11 32 33 414	O)	terface, Fieldbus interface (EtherCAT, EtherNet/IP (other than message communication), PROFINET).
		Extract Color Filter	Convert color image to color extracted image or binary image.	Output result	133.Asc	Result Output (Message)	Output data to the external devices such as a pro- grammable controller or a PC with non-procedure mode via the serial interface or EtherNet/IP (message
	4	Anti Color Shading	To remove the irregular color/pattern by uniformizing max.2 specified colors.				communication). This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.
		Stripes Removal Filter II	Remove the background pattern of vertical, horizontal and diagonal stripes.		OK	Result Display	Used for displaying the texts or the figures in the cam- era image.
		Polar Transformation	Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.	Display result	NG	Display Last NG	Display the last NG images.
-		Trapezoidal Correction	Rectify the trapezoidal deformed image.		8	Image Display Image	Processing item to retain images, including measure-
-	-	Image Subtraction	The registered model image and measurement image are compared and only the different pixels are extract- ed and converted to an image.	*1 2D Code *2 2D Code	es that o	Hold can be read : D can be read : D	ment results. ata Matrix (ECC200) ata Matrix (ECC200), QR Code
ŀ		Advanced filter	Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into	*3 Bar Cod Code 39	les that 9, Codal	can be read : J bar (NW-7), ITF	AN/EAN/UPC (including add-on codes), (Interleaved 2 of 5), Code 93, Code 128, 14 / RSS Limited / RSS Expanded),

28

## Dimensions

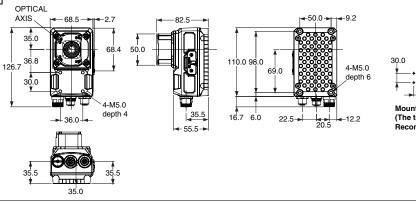
#### **Smart Cameras**

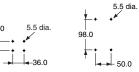
#### C Mount Models



All-in-one Models with Lens Module FHV7H-

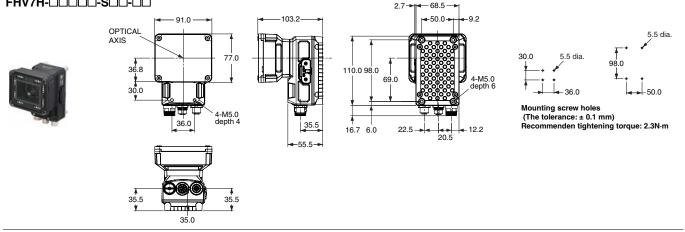






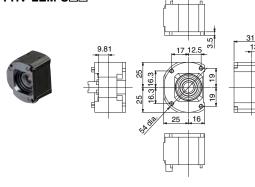
Mounting screw holes (The tolerance: ± 0.1 mm) Recommenden tightening torque: 2.3N·m

# All-in-one Models with Lens and Lighting Modules FHV7H-DDDD-SDD-DD

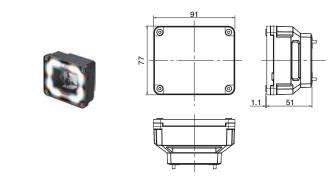


#### **Lens Modules**

Autofocus Lens FHV-LEM-S⊟⊟

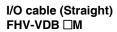


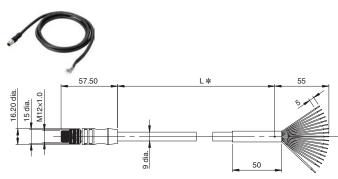
# Lighting Modules



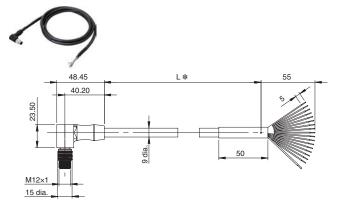
(Unit: mm)

#### Cables

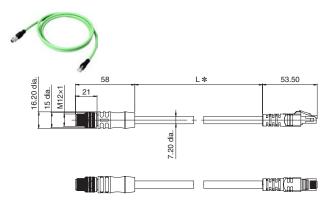




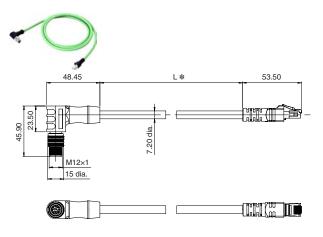
I/O cable (Right angle) FHV-VDLB □M



Ethernet cable (Straight) FHV-VNB □M



Ethernet cable (Right angle) FHV-VNLB



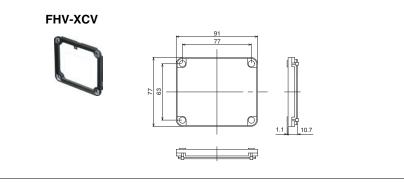
\* Cable is available in 2m/3m/5m/10m/20m.

#### **Optical Filters**

Polarized Light Filter, Diffusion Filter FHV-XDF/-XPL/-XPL-IR

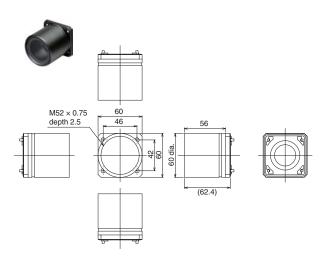


**Light Cover** 

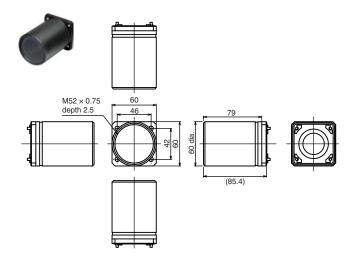


#### Waterproof Hoods

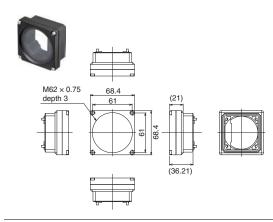
for C-mount Lens (Short) FHV-XHD-S



for C-mount Lens (Long) FHV-XHD-L



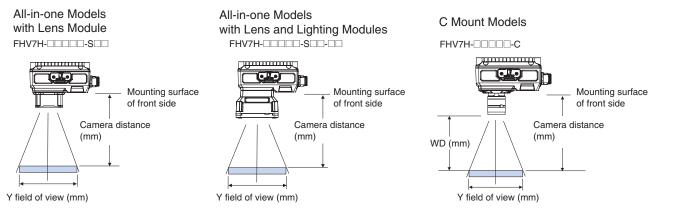
for Lens Modules FHV-XHD-LEM



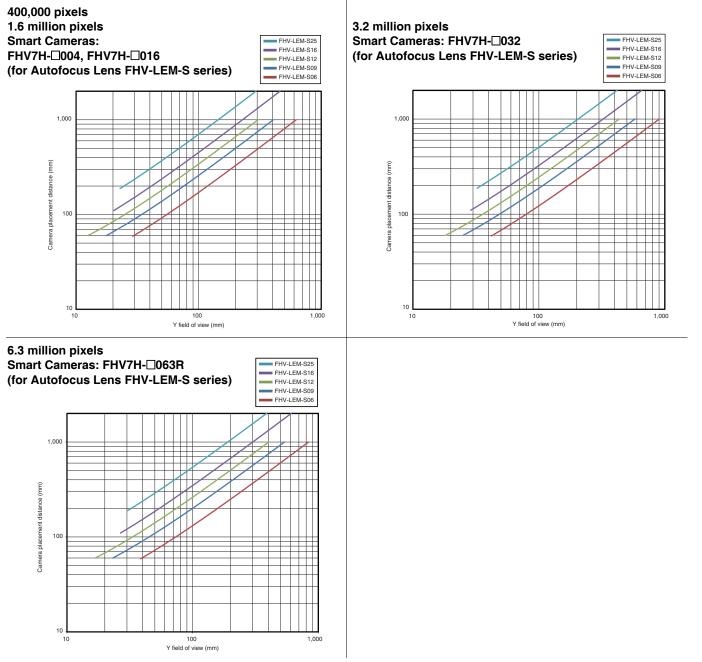
# **Meaning of Optical Chart**

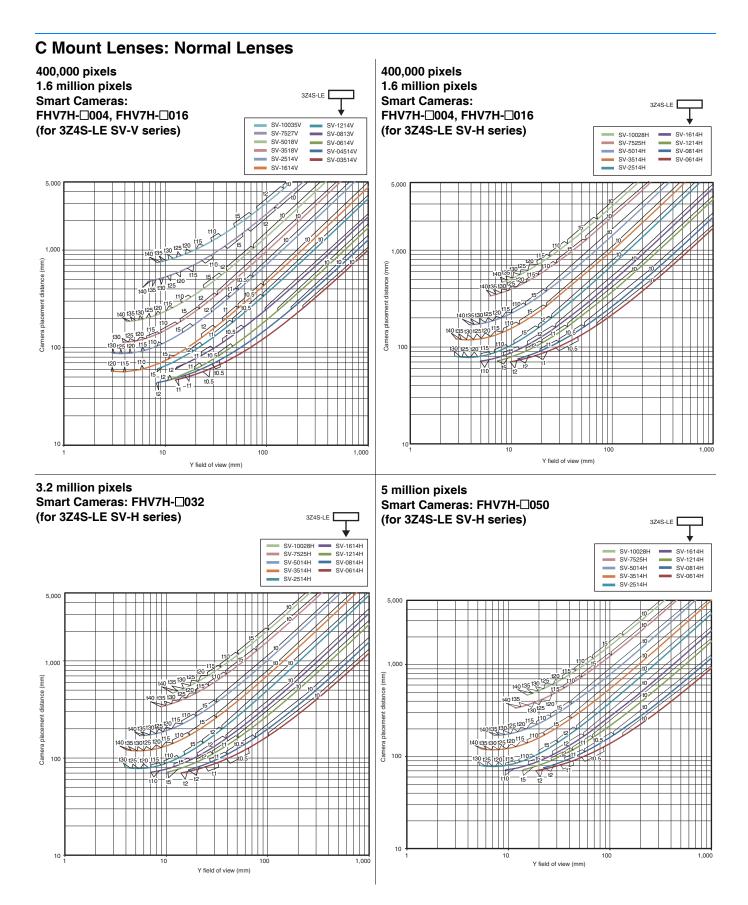
## How-to View the Optical Chart

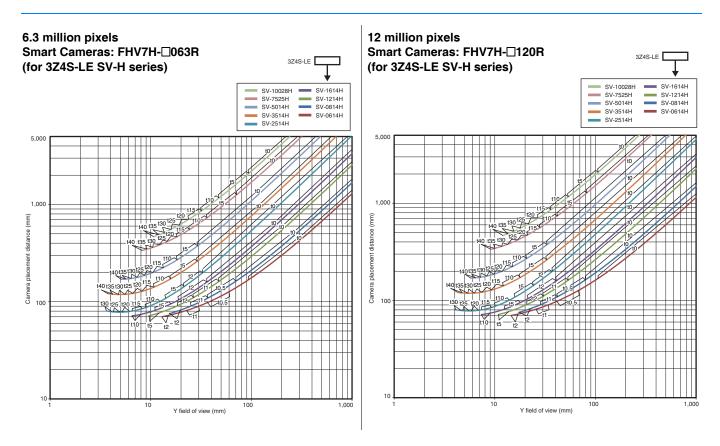
The X axis of the optical chart shows the field of vision (mm). The Y axis of the optical chart shows the camera installation distance (mm). The lengths of the fields of view given in the optical charts are the lengths of the Y axis.



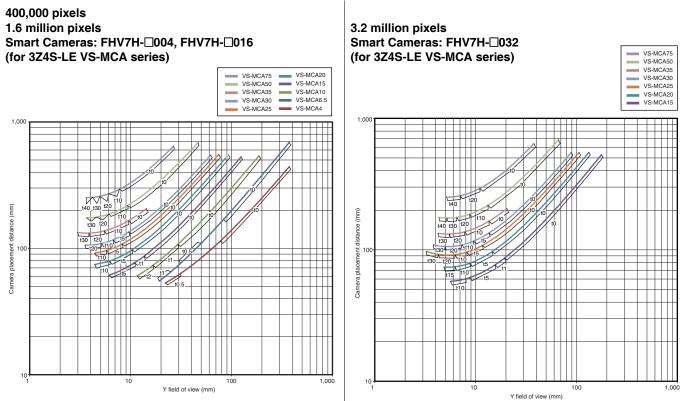
## Lens Modules: Autofocus Lens

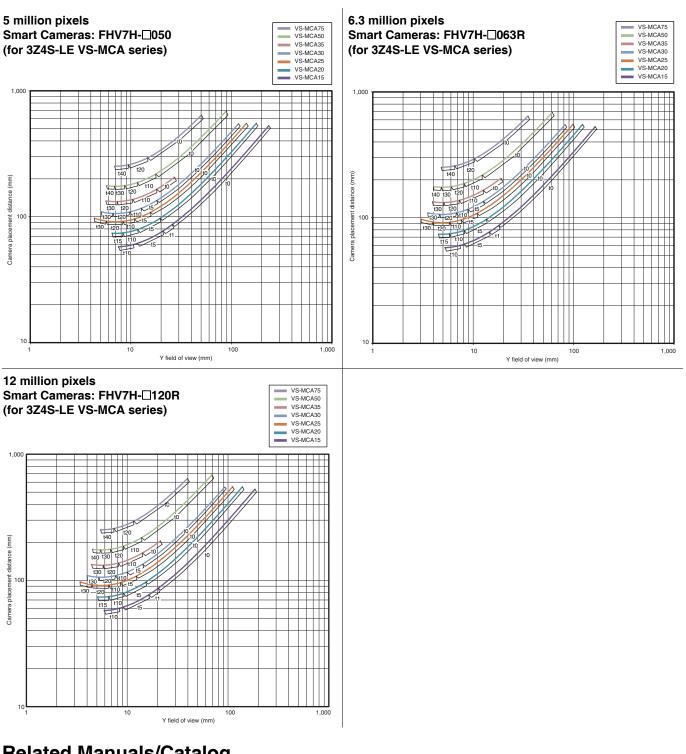






#### C Mount Lenses: Vibration/Shock-resistance Lens





# **Related Manuals/Catalog**

Cat. No.	Series	Manual				
Z365	FH/FHV7/FZ5	Vision System FH/FHV/FZ5 Series User's Manual				
Z341	FH/FHV7/FZ5	Vision System FH/FHV/FZ5 Series Processing Item Function Reference Manual				
Z342	FH/FHV7/FZ5	Vision System FH/FHV/FZ5 Series User's Manual for Communications Settings				
Z408	FHV7	Smart Camera FHV Series Setup Manual				
Q198	FLV/FL	FLV/FL Vision Accessory CATALOG				

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